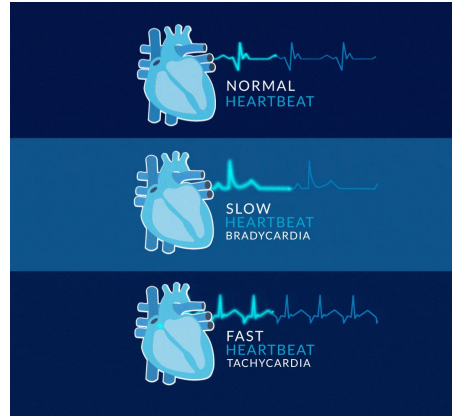
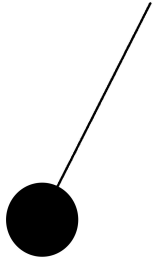


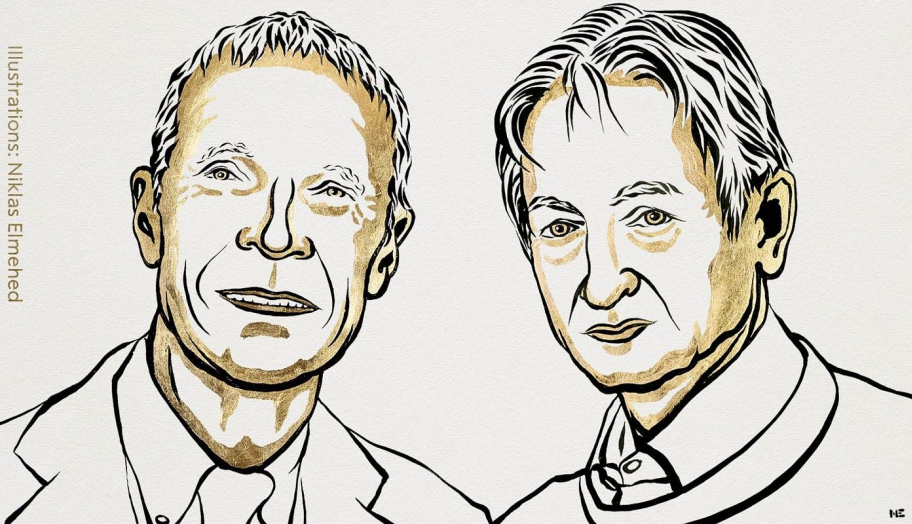
Physics Informed Neural Networks

PINN: An Overview

What Are Dynamical Systems and Why Do They Matter?



THE NOBEL PRIZE IN PHYSICS 2024



John J. Hopfield

Geoffrey E. Hinton

“for foundational discoveries and inventions
that enable machine learning
with artificial neural networks”

THE ROYAL SWEDISH ACADEMY OF SCIENCES

Illustrations: Niklas Elmehed

THE NOBEL PRIZE IN CHEMISTRY 2024



**David
Baker**

**Demis
Hassabis**

**John M.
Jumper**

“for computational
protein design”

“for protein structure prediction”

THE ROYAL SWEDISH ACADEMY OF SCIENCES

Illustrations: Niklas Elmehed

MACHINE LEARNING

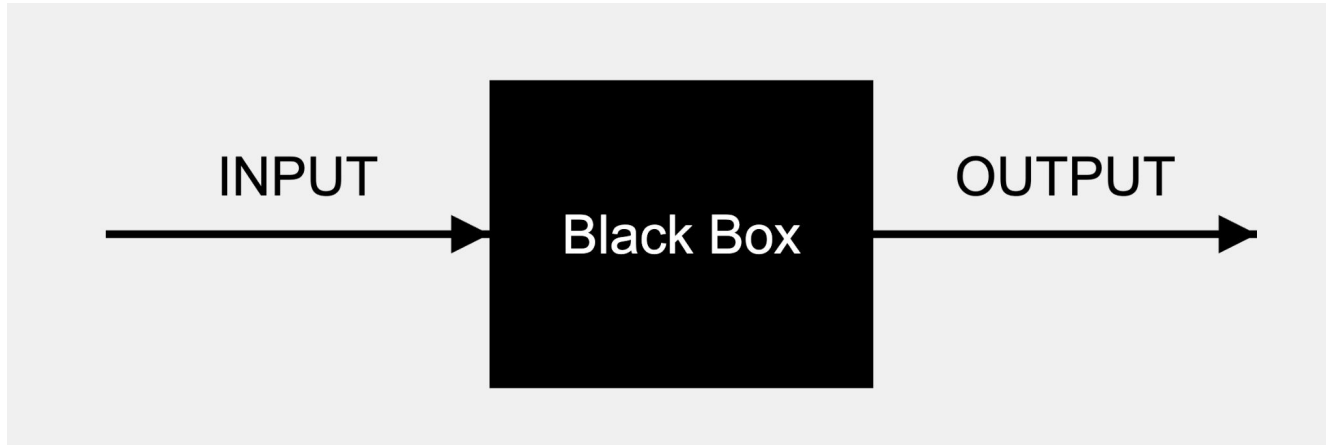
Traditional Programming



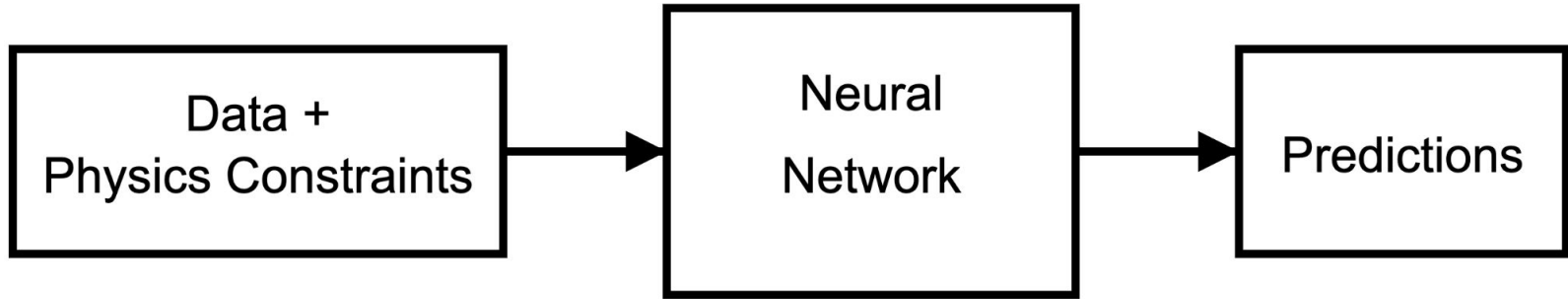
Machine Learning



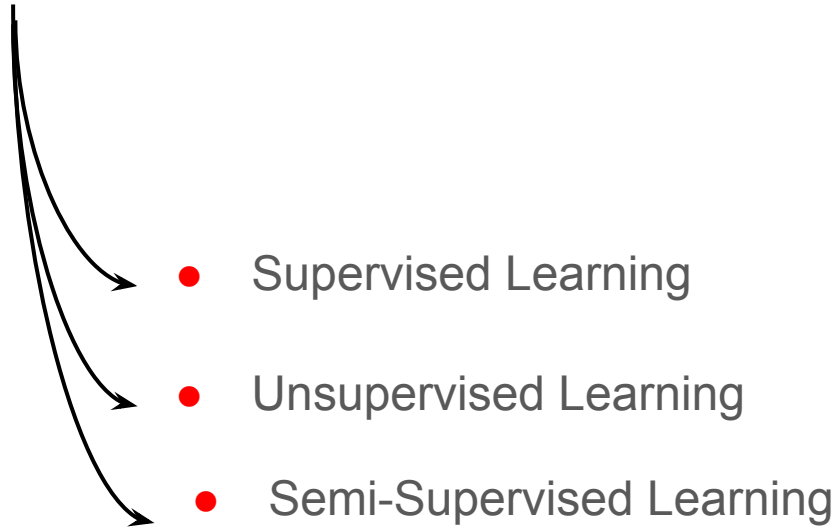
Why Do We Need Better Models?

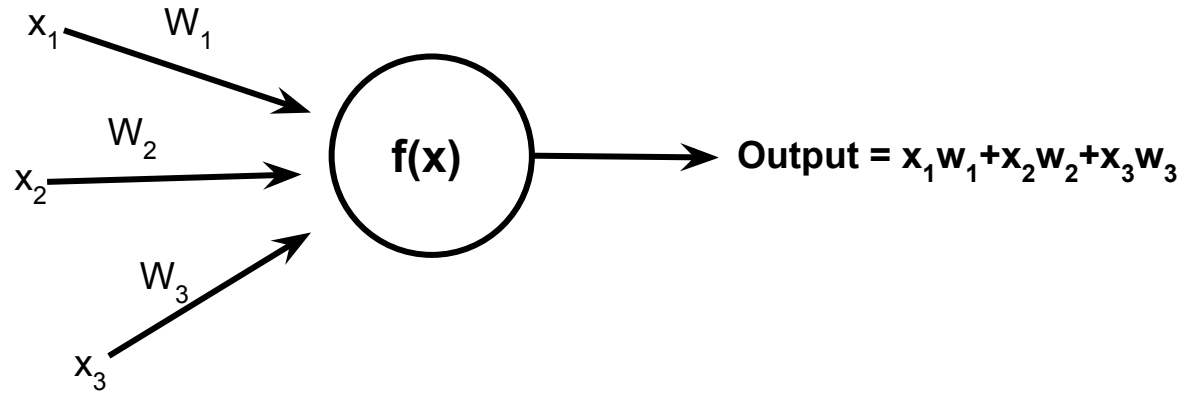


Introducing Physics-Informed Neural Networks (PINNs)

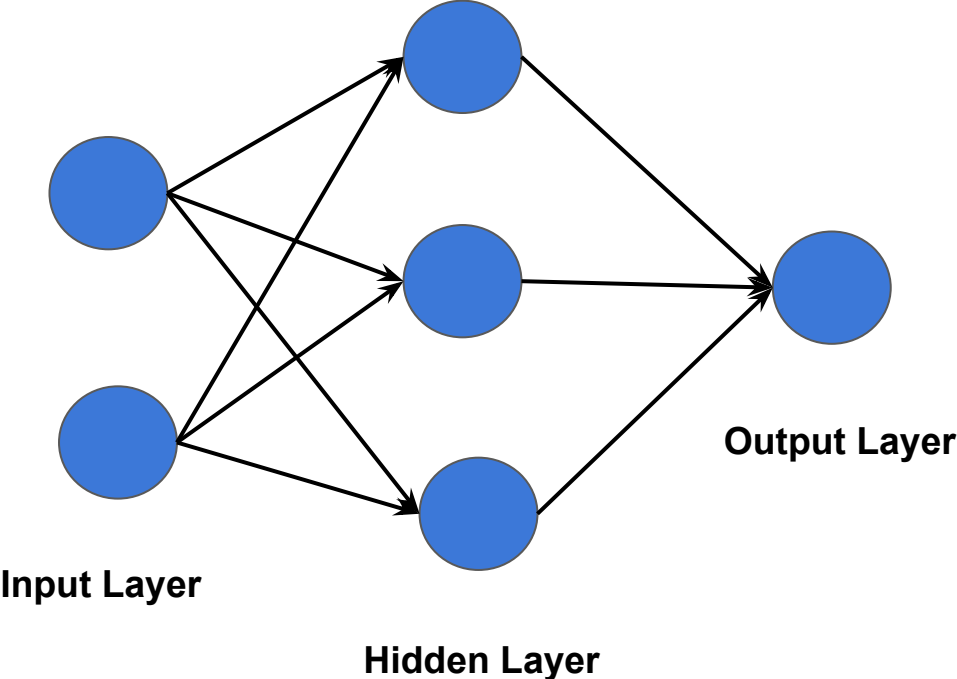


Types

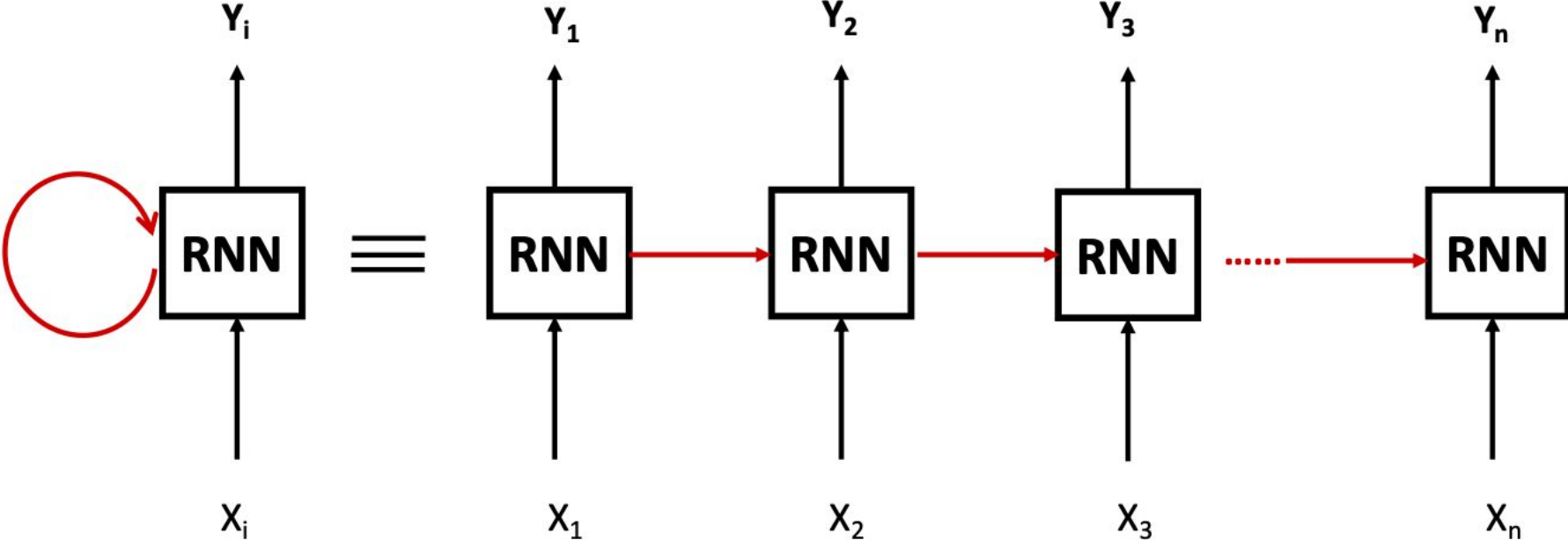




FNN - FeedForward Neural Network



RNN- Recurrent Neural Network



Output

$$y_i^{(1)} = \sigma\left(\sum_{j=0}^n w_{ij}^{(1)} x_j + b_i^{(1)}\right)$$

$$Y^{(1)} = W^{(1)} X + B^{(1)}$$

$$Y^{(2)} = W^{(2)} (W^{(1)} X + B^{(1)}) + B^{(2)}$$

$$FNN(\theta, x) = f^{(n)} \circ f^{(n-1)} \dots f^{(3)} \circ f^{(2)} \circ f^{(1)}(x)$$

$$RNN(\theta, h, x) = f \circ f \dots f \circ f \circ f(h, x)$$

LOSS →

$$L1(\theta) = \frac{1}{N} \sum_{x \in \mathbb{X}} |y - y'|$$

$$L2(\theta) = \frac{1}{N} \sum_{x \in \mathbb{X}} (y - y')^2$$

$$w^{new} = w^{old} - \eta \frac{\partial L}{\partial w^{old}}$$

ACTIVATION FUNCTIONS →

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad ReLU(x) = \max(0, x)$$

$$\tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} \quad softmax(x_i) = \frac{e^{x_i}}{\sum_{j=1}^n e^{x_j}}$$

Romanian Reports in Physics **74**, 113 (2022)

**PRIMER ON SOLVING DIFFERENTIAL EQUATIONS USING MACHINE
LEARNING TECHNIQUES**

TAMIL ARASAN BAKTHAVATCHALAM^{1,2,a}, SELVAKUMAR MURUGAN^{2,b}, SURIYADEEPAN
RAMAMOORTHY^{2,c}, MALAIKANNAN SANKARASUBBU^{2,d}, RADHA RAMASWAMY^{3,e},
VIJAYALAKSHMI SETHURAMAN^{1,f}, BORIS A. MALOMED^{4,g}

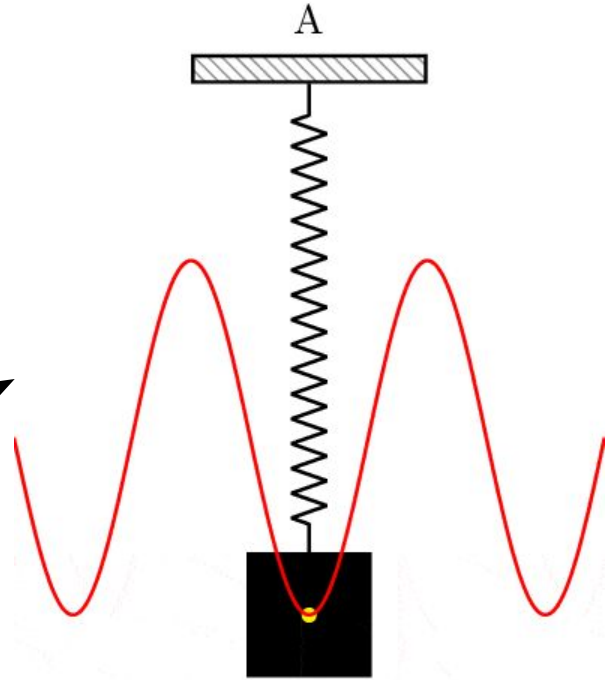
Simple Harmonic Oscillator

$$m \frac{d^2 x}{dt^2} = -kx,$$

$$\frac{d^2 x}{dt^2} + \omega^2 x = 0,$$

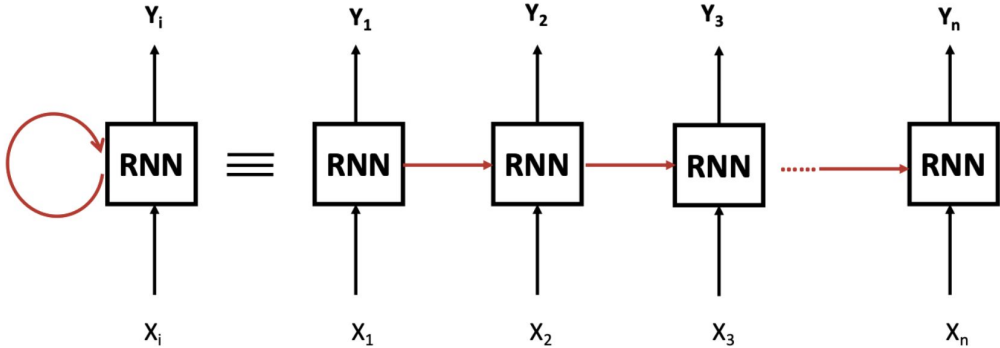
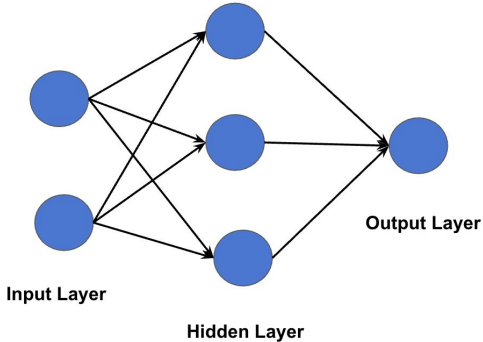
$$x(t) = A \sin \omega t + B \cos \omega t$$

$$x(t) = \cos(\omega t)$$



Neural Network

FNN

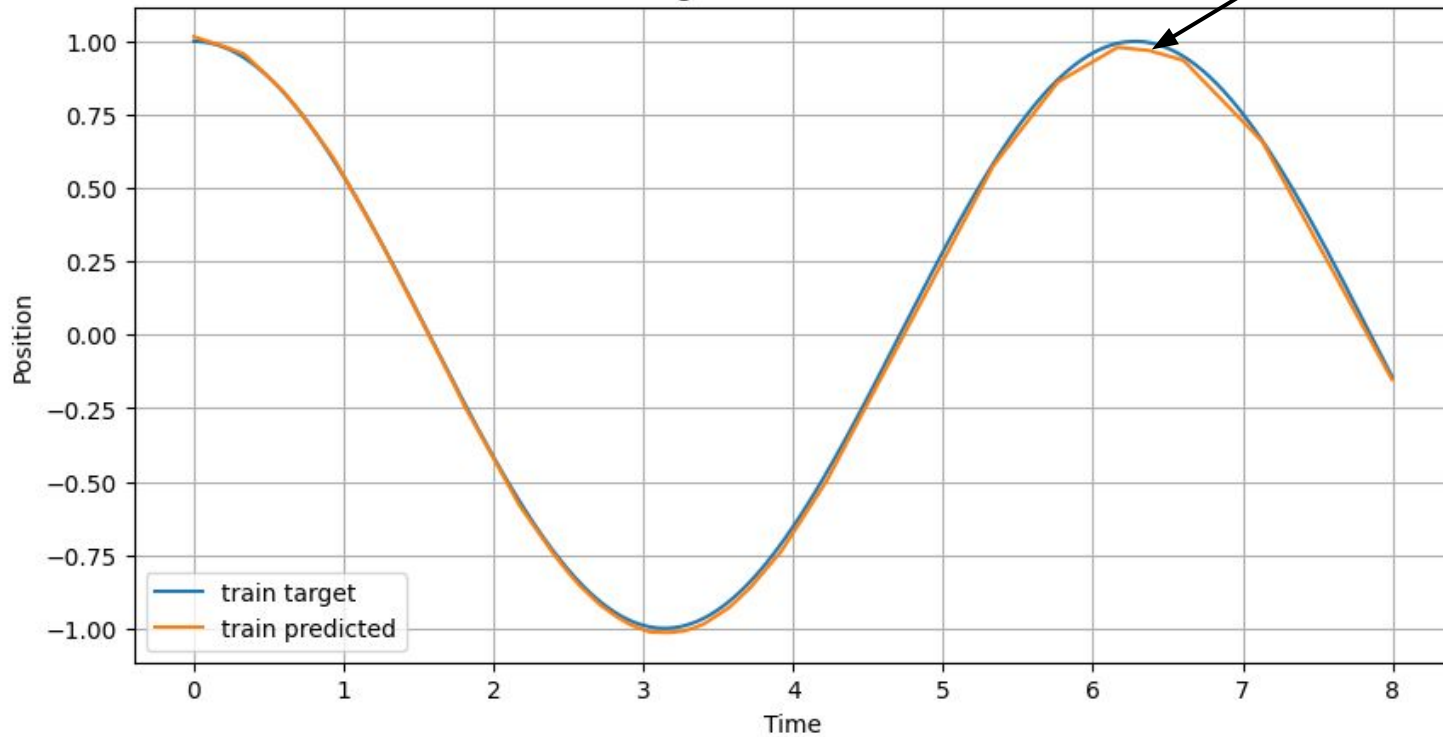


Loss:

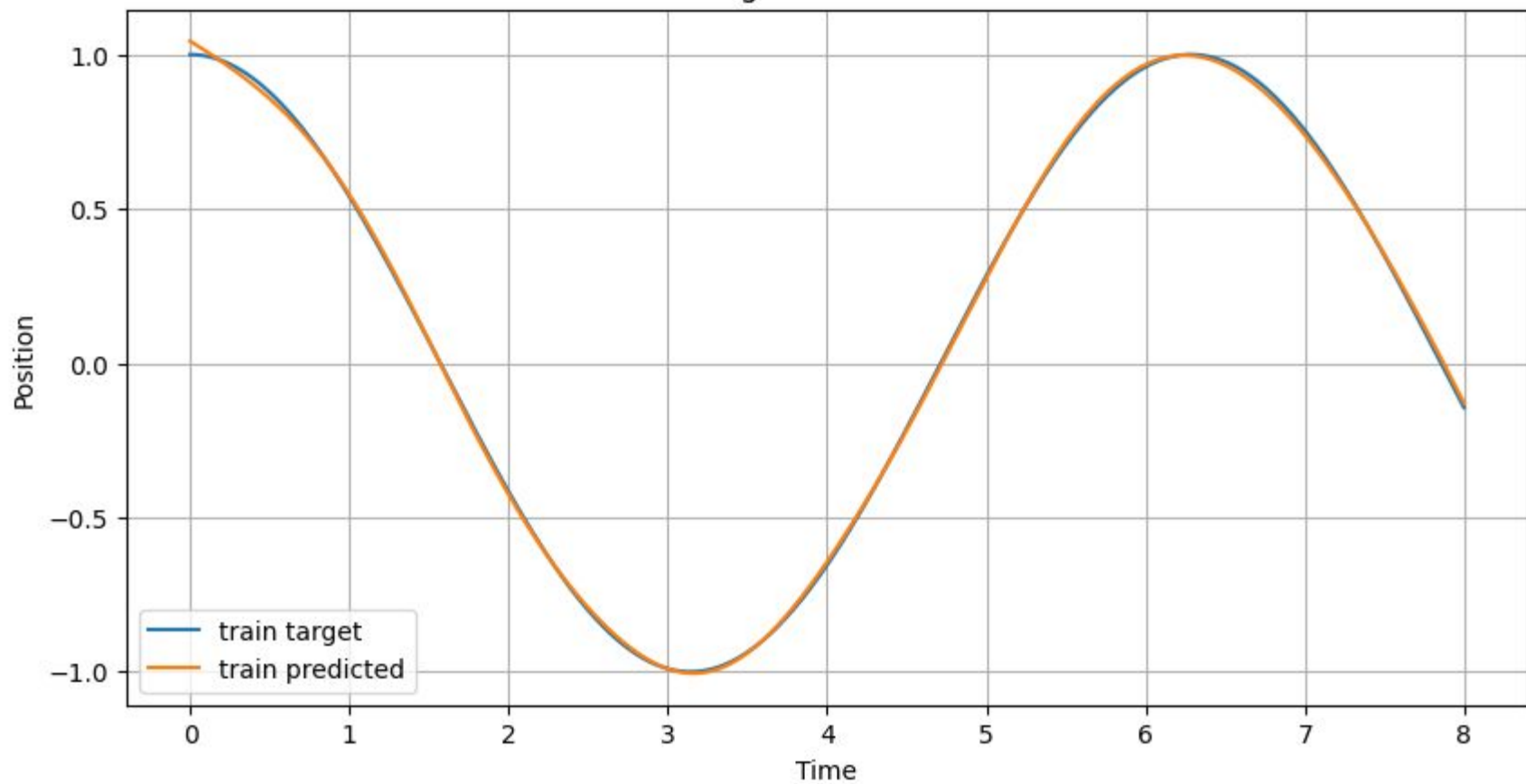
$$\mathcal{L}_{\text{data}} = \frac{1}{N} \sum_{i=1}^N (x_{\text{NN}}(t_i) - x(t_i))^2$$

Train Targets vs. Train Predictions

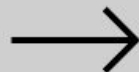
Struggling to capture the pattern



RNN Train Targets vs. Train Predictions



FeedForward



Recurrent



PINN

PINN Loss Function

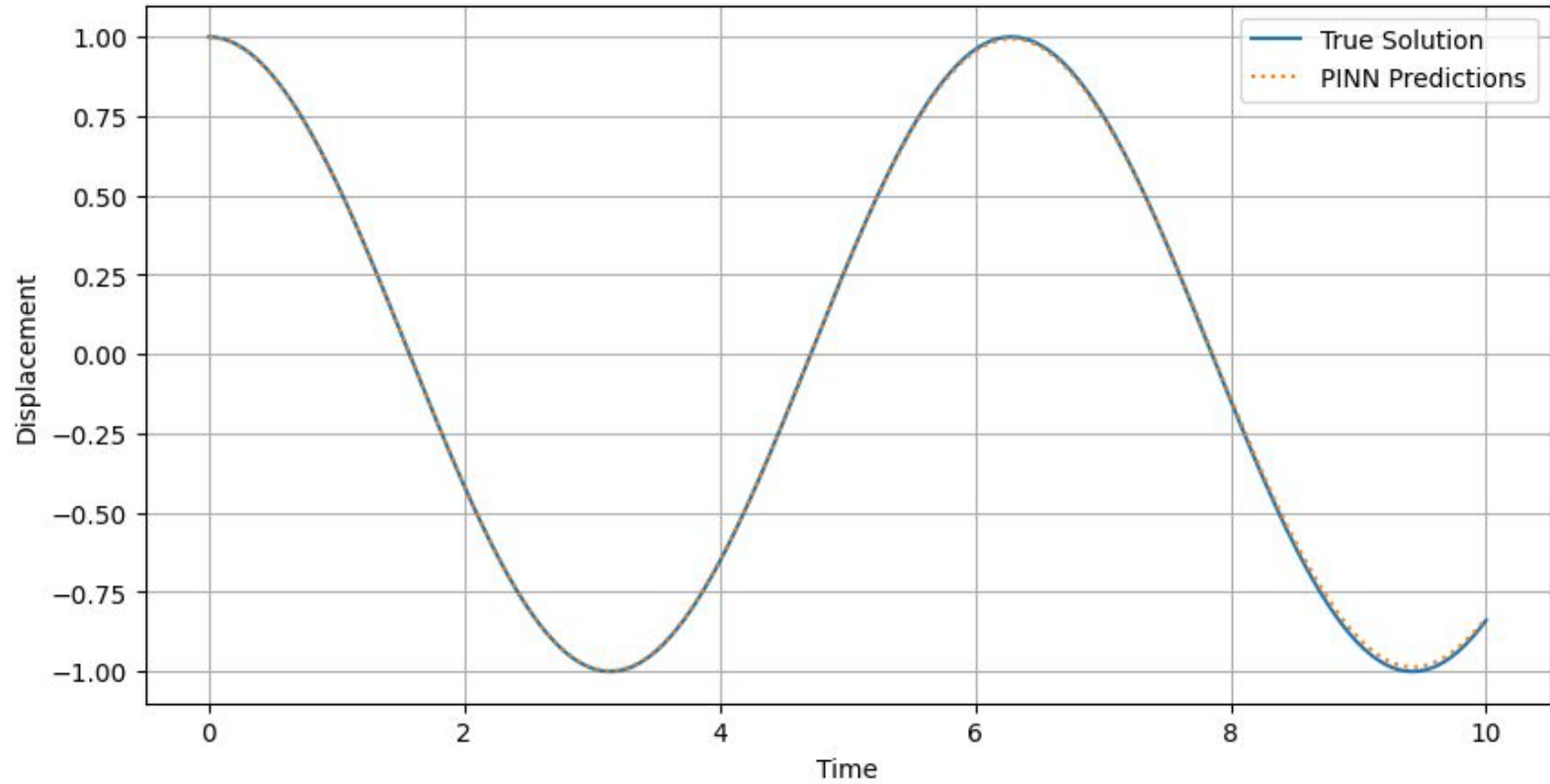
Data Loss + Physics Loss



$$\mathcal{L}_{\text{data}} = \frac{1}{N} \sum_{i=1}^N (x_{\text{PINN}}(t_i) - x(t_i))^2$$

$$\mathcal{L}_{\text{physics}} = \frac{1}{N} \sum_{i=1}^N \left(\frac{d^2}{dt^2} x_{\text{PINN}}(t_i) + \omega^2 x_{\text{PINN}}(t_i) \right)^2$$

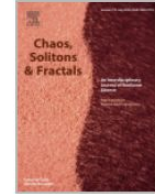
PINN Predictions vs. True SHO Solution





Chaos, Solitons & Fractals

Volume 172, July 2023, 113509



Data-driven multi-valley dark solitons of multi-component Manakov Model using Physics-Informed Neural Networks

Pros of PINN	Cons of PINN
Requires less data due to physics-based constraints.	Slightly higher computational cost due to solving differential equations.
Handles noisy and sparse data effectively.	Requires domain knowledge to encode the governing equations properly.
Provides high interpretability by adhering to physical laws.	May struggle if the governing equations are unknown or highly complex.
Reduces overfitting by enforcing physical constraints.	Implementation can be more challenging compared to traditional neural networks.
Capable of extrapolating beyond training data.	Training may take longer due to physics-informed loss computation.
Ideal for modeling dynamic systems governed by differential equations.	Sensitive to the quality of the equations used.
Ensures stable predictions by constraining solutions to physically valid ones.	Balancing between data loss and physics loss requires careful tuning.

